

Southeast Con 2019 Hardware Competition

FAMU-FSU Engineering

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Introduction To the Competition

The IEEE Southeast Con is a national annual robotics competition that is being hosted in 2019 at the Von Braun Center in Huntsville, Alabama from April 11, 2019 through April 14th, 2019. The robotics competition for this year involves designing an autonomous robot that can clean up debris on the playing field and return home, while also sorting the debris. The debris located on the field will also vary between four different colors. During the competition, multiple other robots will be actively playing against each other and points will be deducted if robots collide.

Objective

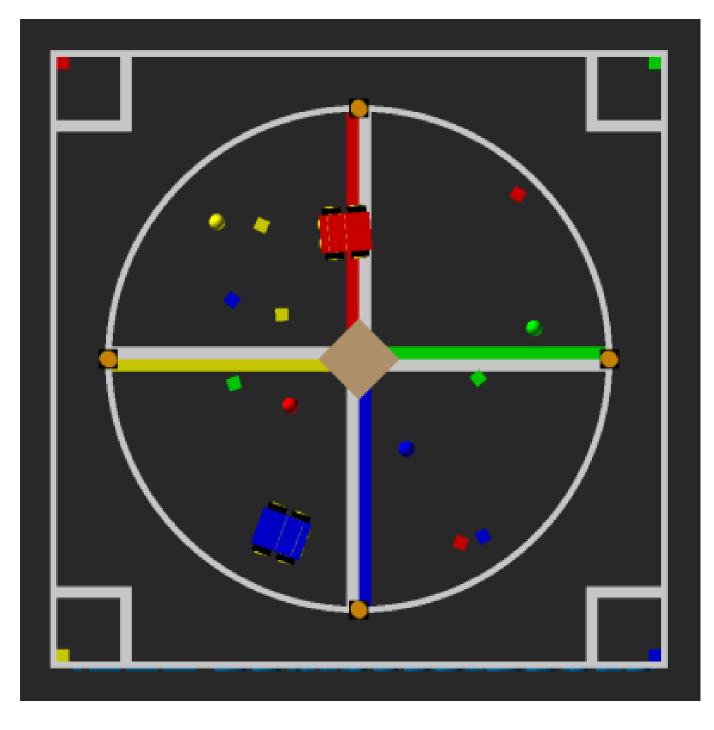
To clear orbital space debris while avoiding Spacetels and return to home base within the time limit of three minutes. The score is determined by a number of factors including:

- 1) the number of complete playing field orbits
- 2) the number and type of space debris cleared
- 3) sorting cleared debris
- 4) returning to assigned corner square (home base)
- 5) avoiding collision with Spacetels.

Competition Constraints

- The robot must fit within a 9 in x 9 in x 11 in cube while moving $(L \times W \times H)$
- The robot must be entirely self-contained
- When not in motion the robot can extend a maximum of 3 in x 3 in (L x W)
- The extension must be physically connected to the robot at all times
- Pyrotechnics, compressed gas, hydrocarbons, toxic or corrosive materials are not allowed
- The robot must have a 1-inch high bumper around 80 % of its perimeter

Leave h
Cross th only)
For each within Z closest t
Debris r
Debris p remova
Color-m color co
Finish in
At concl onboard
Every co



Point System

Task

nome base and enter Zone 1

ne orbital line into Zone 2 (first time

h complete, counter-clockwise orbit Zone 2, starting from the quadrant to designated corner square

removed from Zone 2 (each)

placed in home base (additional to

atched debris placed in appropriated orner square (bonus points)

n your home base

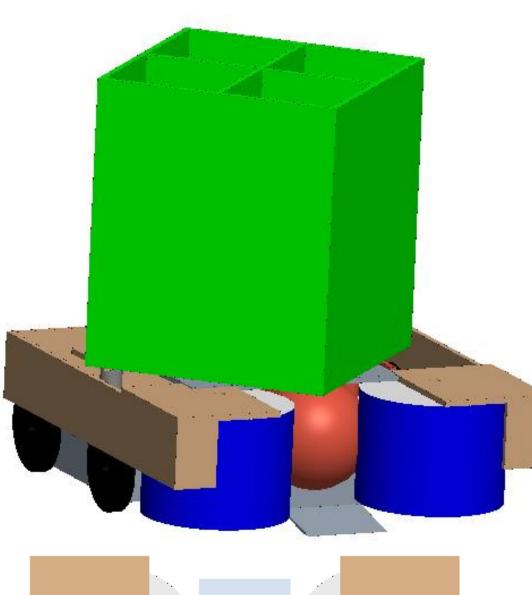
usion of debris removal, raise your

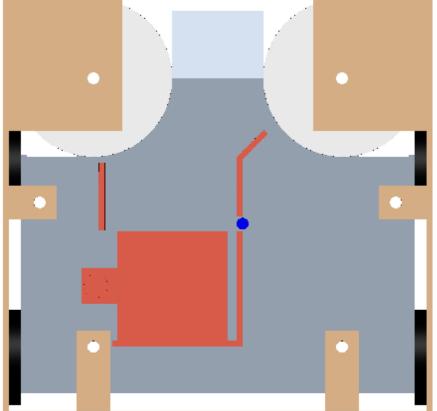
I flag while in home base

ollision with a Spacetel

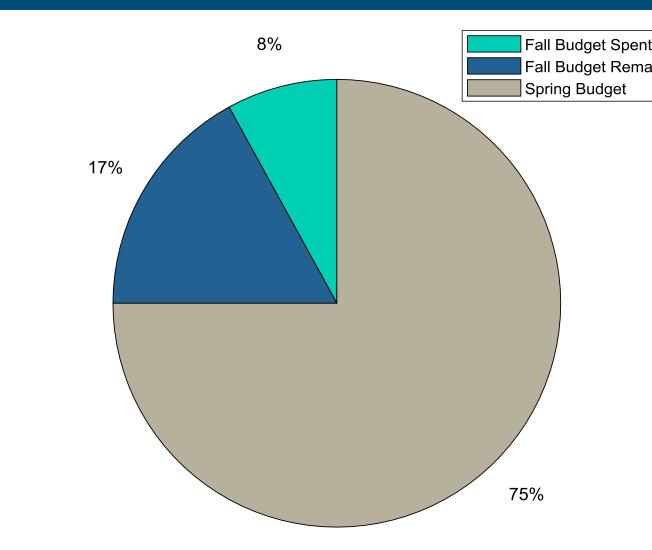
Playing Field

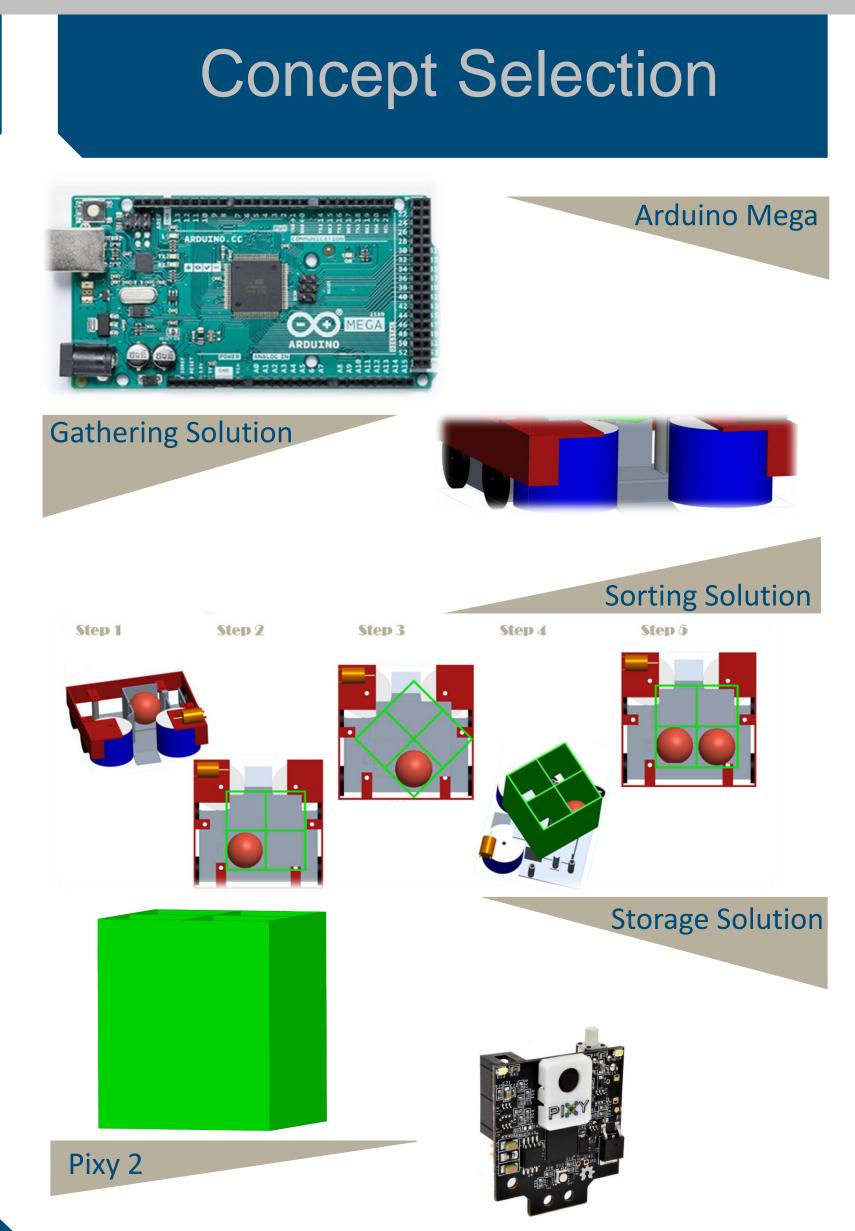
Overall Design





Budget





Future Plans

Move to the final model of the robot, this includes:

- Multiple modular components to meet the challenge of the other robots
- Meet the targets that were laid out during the 2018 Fall Planning Section
- Move to more lightweight design, compared to test material.